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# Technical Note

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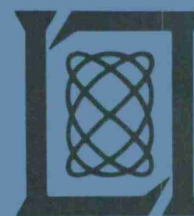
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A NEW GEOMETRICAL THEOREM DISCOVERED  
WITH THE AID OF A COMPUTER

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# ABSTRACT

In the course of a computer study of a new form of ball bearing, a curious invariance was noted. This led to a new theorem in the geometry of circles. A proof for this theorem, together with a useful lemma, is the subject of this Technical Note.

Accepted for the Air Force  
Joseph R. Waterman, Lt. Col., USAF  
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# A NEW GEOMETRICAL THEOREM DISCOVERED WITH THE AID OF A COMPUTER

Let  $\Gamma$  and  $\tilde{\Gamma}$  be two circles in euclidean 3-space,  $R^3$ . Suppose there is a number  $x$  such that: (1) every point on either circle is distance  $x$  from exactly two points on the other circle. We can then select a point  $Z_1$  on  $\Gamma$  and draw a zig-zag line between the two circles as follows:

Select  $\tilde{Z}_1$  on  $\tilde{\Gamma}$  with  $|\tilde{Z}_1 - Z_1| = x$

Select  $Z_2 \neq Z_1$  on  $\Gamma$  with  $|Z_2 - \tilde{Z}_1| = x$

Select  $\tilde{Z}_2 \neq \tilde{Z}_1$  on  $\tilde{\Gamma}$  with  $|\tilde{Z}_2 - Z_2| = x$

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Select  $Z_{n+1} \neq Z_n$  on  $\Gamma$  with  $|Z_{n+1} - \tilde{Z}_n| = x$

Select  $\tilde{Z}_{n+1} \neq \tilde{Z}_n$  on  $\tilde{\Gamma}$  with  $|\tilde{Z}_{n+1} - Z_{n+1}| = x$  .

It may happen (illustrated for the case  $n = 3$  in Fig. 1) that  $Z_{n+1} = Z_1$ . We show that if this occurs, the zig-zag line can be started at any point on  $\Gamma$  and it will still close.

This remarkable fact was observed while performing certain calculations about ball bearings on a computer<sup>1</sup>. The theorem bears a superficial resemblance to Steiner's Porism<sup>2</sup> but cannot be proved the same way.

Condition (1) is not as formidable as it may appear. If both circles lie in the same plane, with radii  $r$  and  $\bar{r}$  and with centers separated by  $\delta$ , elementary calculus shows that (1) is equivalent to the two inequalities:

$$\begin{aligned} |r - \bar{r}| &< x - \delta \\ x + \delta &< r + \bar{r} \end{aligned}$$

Thus suitable  $x$ 's will exist provided the smaller circle encloses the center of the larger one.

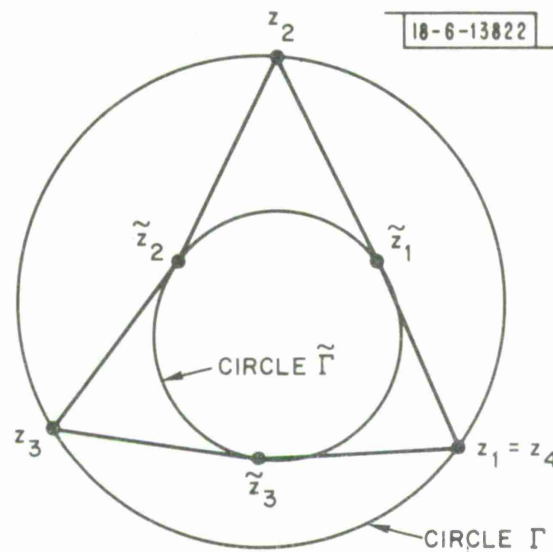


Fig. 1. Each straight line has length  $x$ ,  $n = 3$ .

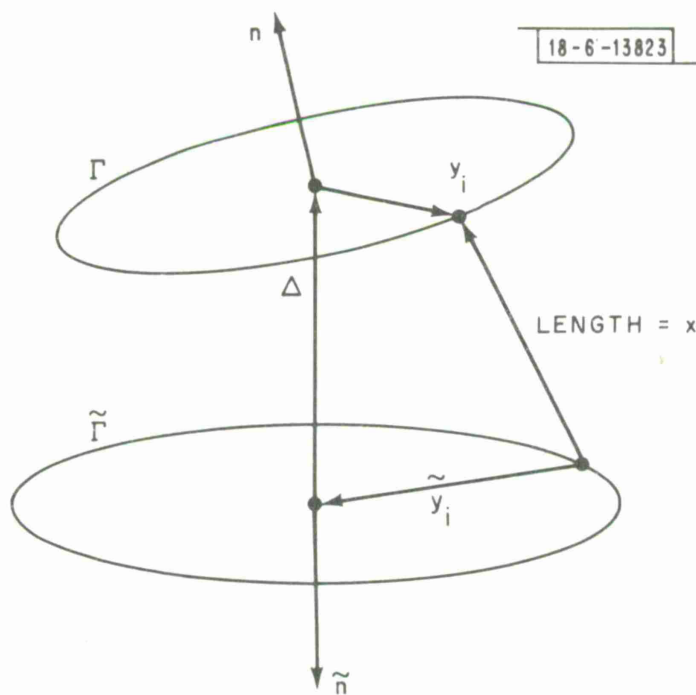


Fig. 2. Illustrating the notation used in the computation of  $f$ .



The proof proceeds as follows: Suppose for some choice of  $Z_1$ , say  $Z_1 = p$ ,  $Z_{n+1} = Z_1$ . We parametrize  $\Gamma$  by  $s$ , the directed arc length measured from  $p$ . Thus we can view  $Z_1$ , and thus  $Z_{n+1}$ , and ultimately  $t$ , the arc length from  $p$  to  $Z_{n+1}$  as functions of  $s$ . Below we show that there is a smooth function  $f$  of  $s$  and  $t$  with properties:

$$(i.) f(s,s) = 1 \text{ for all } s$$

$$(ii.) f(s,t) = \frac{dt}{ds}$$

Application of a well known uniqueness theorem<sup>3</sup> assures us that this ordinary differential equation:

$$\frac{dt}{ds} = f(s,t)$$

$$t(0) = 0$$

has only one solution. By (i),  $t(s) = s$  is the solution. But this implies that  $Z_{n+1} = Z_1$  for all  $Z_1$ .

In constructing  $f$  we will need the following lemma:

Lemma: Let  $B, n, Z_1$  and  $Z_2$  be vectors in  $R^3$ , satisfying:

$$(a.) |y_1| = |y_2|$$

$$(b.) |B + y_1| = |B + y_2|$$

$$(c.) n \cdot y_1 = n \cdot y_2$$

$$(d.) y_1 \neq y_2$$

Then:

$$B \times n \cdot (y_1 + y_2) = 0$$

Proof: If  $B$  and  $n$  are dependent the result is obvious. If not, by squaring (b) and (a) and taking the difference we obtain:

$$(e.) B \cdot y_1 = B \cdot y_2$$

In conjunction with (c), (e) shows that  $y_1$  and  $y_2$  have the same orthogonal projection on the plane spanned by  $B$  and  $n$ . By (a) and (d) the components of  $y_1$  and  $y_2$  normal to this plane must be equal and opposite, so  $y_1 + y_2$  lies in the  $B, n$  plane. From this the conclusion is evident.

We can now compute  $f$ . We will use the following notation:

$n$  is the unit normal to circle  $\Gamma$

$\tilde{n}$  " " " "  $\tilde{\Gamma}$

$y_i$  is the vector from the center of  $\Gamma$  to  $Z_i$

$\tilde{y}_i$  is the negative of the vector from the center of  $\tilde{\Gamma}$  to  $\tilde{Z}_i$ .

$\Delta$  is the vector from the center of  $\tilde{\Gamma}$  to the center of  $\Gamma$ .

Figure two illustrates this notation. Imagine a slight motion of  $y_1$  along the circle. Since  $dy_1$  is perpendicular to both  $n$  and  $y_1$  we can write:

$$dy_1 = n \times \frac{y_1}{|y_1|} |dy_1| \quad (2)$$

As  $y_1$  moves,  $\tilde{y}_1$  also must move, keeping

$$|\Delta + y_1 + \tilde{y}_1| = x \quad (3)$$

Squaring (3) and differentiating gives:

$$(\Delta + y_1 + \tilde{y}_1) \cdot (dy_1 + d\tilde{y}_1) = 0 \quad (4)$$

Substituting into (4), (2) and (5) where:

$$d\tilde{y}_1 = \tilde{n} \times \frac{\tilde{y}_1}{|\tilde{y}_1|} |d\tilde{y}_1| \quad (5)$$

gives:

$$(\Delta + \tilde{y}_1) \cdot n \times \frac{y_1}{|y_1|} |dy_1| + (\Delta + y_1) \cdot \tilde{n} \times \frac{\tilde{y}_1}{|\tilde{y}_1|} |d\tilde{y}_1| = 0 \quad (6)$$

Thus:

$$\frac{|d\tilde{y}_1|}{|dy_1|} = - \frac{|\tilde{y}_1| (\Delta + \tilde{y}_1) \cdot n \times y_1}{|y_1| (\Delta + y_1) \cdot \tilde{n} \times \tilde{y}_1} \quad (7)$$

Similarly,

$$\frac{|dy_2|}{|d\tilde{y}_1|} = - \frac{|y_2| (\Delta + y_2) \cdot \tilde{n} \times \tilde{y}_1}{|\tilde{y}_1| (\Delta + \tilde{y}_1) \cdot n \times y_2} \quad (8)$$

Multiplying (7) by (8) and using the lemma in the forms:

$$(\Delta + \tilde{y}_1) \cdot n \times y_1 = - (\Delta + \tilde{y}_1) \cdot n \times y_2$$

$$(\Delta + y_2) \cdot \tilde{n} \times \tilde{y}_1 = - (\Delta + y_2) \cdot \tilde{n} \times \tilde{y}_2$$

gives:

$$\frac{|dy_2|}{|dy_1|} = \frac{(\Delta + y_2) \cdot \tilde{n} \times \tilde{y}_2}{(\Delta + y_1) \cdot \tilde{n} \times \tilde{y}_1} \quad (9)$$

Multiplying  $n$  similar expressions gives:

$$\frac{dt}{ds} = \frac{|dy_{n+1}|}{|dy_1|} = \frac{(\Delta + y_{n+1}) \cdot \tilde{n} \times \tilde{y}_{n+1}}{(\Delta + y_1) \cdot \tilde{n} \times \tilde{y}_1} = f(s, t)$$

Clearly if  $z_{n+1} = z_1$ , then  $y_{n+1} = y_1$  and  $\tilde{y}_{n+1} = \tilde{y}_1$ , whence:

$$f(s, s) = 1 \quad .$$

This completes the proof.

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2. H. S. M. Coxeter and M. C. Greitzer, Geometry Revisited, Random House, pp. 124, 125 (1967).
3. E. A. Coddington and N. Levinson, Theory of Ordinary Differential Equations, McGraw-Hill, New York, p. 10 (1955).

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